## Math 3406 HW9

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**Problem 1.** Assume that A is a matrix that can be diagonalized. Show that

$$\det(e^{At}) = e^{\operatorname{Tr}(A)t}$$

Since A is diagonalizable, it can be expressed as  $A = PDP^{-1}$ , where P is an invertible matrix and D is a diagonal matrix whose diagonal entries are the eigenvalues  $\lambda_1, \lambda_2, \ldots, \lambda_n$  of A. The exponential of A is given by:

$$e^{At} = P e^{Dt} P^{-1}.$$

The expression of the exponential for the diagonalizable matrix:

$$e^{A} = \sum_{n=0}^{\infty} \frac{(PDP^{-1})^{n}}{n!} = \sum_{n=0}^{\infty} \frac{PD^{n}P^{-1}}{n!} = P\left(\sum_{n=0}^{\infty} \frac{D^{n}}{n!}\right)P^{-1}$$

The matrix  $e^{Dt}$  is diagonal with entries  $e^{\lambda_i t}$ , thus:

$$\det(e^{At}) = \det(Pe^{Dt}P^{-1}) = \det(P)\det(e^{Dt})\det(P^{-1}) = \det(e^{Dt}) = e^{\lambda_1 t + \lambda_2 t + \dots + \lambda_n t}$$

The trace of A is the sum of its eigenvalues:

$$\operatorname{Tr}(A) = \lambda_1 + \lambda_2 + \dots + \lambda_n.$$

Thus, we have:

$$\det(e^{At}) = e^{\operatorname{Tr}(A)t}.$$

Problem 2. Let

$$P = \begin{vmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \end{vmatrix}$$

Find the eigenvalues and eigenvectors of the matrix  $2I - P - P^3$ .

$$2I - P - P^{3} = \begin{bmatrix} 2 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 2 \end{bmatrix} - \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \end{bmatrix} - \begin{bmatrix} 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix} = \begin{bmatrix} 2 & -1 & 0 & -1 \\ -1 & 2 & -1 & 0 \\ 0 & -1 & 2 & -1 \\ -1 & 0 & -1 & 2 \end{bmatrix}$$

$$\begin{bmatrix} 2-\lambda & -1 & 0 & -1 \\ -1 & 2-\lambda & -1 & 0 \\ 0 & -1 & 2-\lambda & -1 \\ -1 & 0 & -1 & 2-\lambda \end{bmatrix}.$$

The determinant of the obtained matrix is  $\lambda(\lambda - 4)(\lambda - 2)^2$ . Solve the equation  $\lambda(\lambda - 4)(\lambda - 2)^2 = 0$ . The roots are:  $\lambda_1 = 4, \lambda_2 = 2, \lambda_3 = 2, \lambda_4 = 0$ . Next, find the eigenvectors for each eigenvalue: For  $\lambda = 4$ :

$$\begin{bmatrix} 2-\lambda & -1 & 0 & -1\\ -1 & 2-\lambda & -1 & 0\\ 0 & -1 & 2-\lambda & -1\\ -1 & 0 & -1 & 2-\lambda \end{bmatrix} = \begin{bmatrix} -2 & -1 & 0 & -1\\ -1 & -2 & -1 & 0\\ 0 & -1 & -2 & -1\\ -1 & 0 & -1 & -2 \end{bmatrix},$$
  
The eigenvector of this matrix is 
$$\begin{bmatrix} -1\\ 1\\ -1\\ 1 \end{bmatrix}.$$
  
For  $\lambda = 2$ :

$$\begin{bmatrix} 2-\lambda & -1 & 0 & -1\\ -1 & 2-\lambda & -1 & 0\\ 0 & -1 & 2-\lambda & -1\\ -1 & 0 & -1 & 2-\lambda \end{bmatrix} = \begin{bmatrix} 0 & -1 & 0 & -1\\ -1 & 0 & -1 & 0\\ 0 & -1 & 0 & -1\\ -1 & 0 & -1 & 0 \end{bmatrix},$$
  
The eigenvectors of this matrix is 
$$\begin{bmatrix} -1\\ 0\\ 1\\ 0\\ 1 \end{bmatrix}, \begin{bmatrix} 0\\ -1\\ 0\\ 1\\ 0\\ 1 \end{bmatrix}.$$

For 
$$\lambda = 0$$
:  

$$\begin{bmatrix}
2 - \lambda & -1 & 0 & -1 \\
-1 & 2 - \lambda & -1 & 0 \\
0 & -1 & 2 - \lambda & -1 \\
-1 & 0 & -1 & 2 - \lambda
\end{bmatrix} =
\begin{bmatrix}
2 & -1 & 0 & -1 \\
-1 & 2 & -1 & 0 \\
0 & -1 & 2 & -1 \\
-1 & 0 & -1 & 2
\end{bmatrix},$$
The eigenvector of this matrix is  $\begin{bmatrix}
1 \\
1 \\
1 \\
1
\end{bmatrix}$ .

**Problem 3.** Solve the system

$$\frac{d\vec{u}}{dt} = A\vec{u}, \quad \vec{u}(0) = \begin{bmatrix} 4\\1 \end{bmatrix}.$$

where

$$A = \begin{bmatrix} -2 & 3\\ 2 & -3 \end{bmatrix}$$

Compute  $\lim_{t\to\infty} \vec{u}(t)$ .

We first find the eigenvalue and eigenvector of the matrix A, we use the trick to compute  $2 \times 2$  matrix, and get:

$$-5: \begin{bmatrix} -1\\1 \end{bmatrix} \to e^{-5t} \begin{bmatrix} -1\\1 \end{bmatrix}$$
$$0: \begin{bmatrix} 3\\2 \end{bmatrix} \to e^{0t} \begin{bmatrix} 3\\2 \end{bmatrix}$$
$$\vec{u}(t) = c_1 e^{-5t} \begin{bmatrix} -1\\1 \end{bmatrix} + c_2 e^{0t} \begin{bmatrix} 3\\2 \end{bmatrix}, \text{ where } c_1, c_2 \text{ are constants.}$$

Applying the initial condition  $\vec{u}(0) = \begin{vmatrix} 4 \\ 1 \end{vmatrix}$ , we have:

$$\begin{bmatrix} 4\\1 \end{bmatrix} = c_1 \begin{bmatrix} -1\\1 \end{bmatrix} + c_2 \begin{bmatrix} 3\\2 \end{bmatrix}$$
$$c_1 = -1 \text{ and } c_2 = 1$$

To compute  $\lim_{t\to\infty} \vec{u}(t)$ , we observe the terms involving  $e^{-5t}$  and  $e^{0t}$ . Since  $e^{-5t}$  approaches 0 as t goes to infinity, the term  $c_1 e^{-5t} \begin{bmatrix} -1\\ 1 \end{bmatrix}$  will vanish, leaving us with:

$$\lim_{t \to \infty} \vec{u}(t) = \lim_{t \to \infty} \left( c_1 e^{-5t} \begin{bmatrix} -1\\1 \end{bmatrix} + c_2 e^{0t} \begin{bmatrix} 3\\2 \end{bmatrix} \right) = \begin{bmatrix} 3\\2 \end{bmatrix}$$

**Problem 4.** For the matrix  $A = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$ , find  $e^{At}$  using the power series. The matrix A has two eigenvalues  $\lambda_1 = +1$  and  $\lambda_2 = -1$  (corresponding to exponentially growing and decaying solutions to  $\frac{d\vec{x}}{dt} = A\vec{x}$ , respectively). The corresponding eigenvectors are:

$$\vec{x}_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \quad \vec{x}_2 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}.$$

Hence, the matrix exponential should be:

$$e^{At} = \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} e^t & 0 \\ 0 & e^{-t} \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}^{-1}$$
$$= \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} e^t \\ e^{-t} \end{bmatrix} \frac{1}{2} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$$
$$= \frac{1}{2} \begin{bmatrix} e^t & e^{-t} \\ e^t & -e^{-t} \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$$
$$= \frac{1}{2} \begin{bmatrix} e^t + e^{-t} & e^t - e^{-t} \\ e^t - e^{-t} & e^t + e^{-t} \end{bmatrix}.$$

**Problem 5.** Generally,  $e^A e^B \neq e^{A+B}$ . Check this for the given matrices:

$$A = \begin{bmatrix} 1 & 4 \\ 0 & 0 \end{bmatrix}, \quad B = \begin{bmatrix} 0 & -4 \\ 0 & 0 \end{bmatrix}, \quad A + B = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$$

Calculate  $e^A$ ,  $e^B$ , and  $e^{A+B}$  and verify whether  $e^A e^B = e^{A+B}$ .

$$e^{A} = \begin{bmatrix} e & -4\\ 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} 1 & 4\\ 0 & 1 \end{bmatrix} = \begin{bmatrix} e & 4(-1+e)\\ 0 & 1 \end{bmatrix}$$
$$e^{B} = \begin{bmatrix} 1 & 0\\ 0 & 1 \end{bmatrix} + \begin{bmatrix} 0 & -4\\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & -4\\ 0 & 1 \end{bmatrix}$$
$$e^{A+B} = \begin{bmatrix} e & 0\\ 0 & 1 \end{bmatrix}$$

 $e^{A}e^{B} = \begin{bmatrix} e & -4+4e \\ 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} 1 & -4 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} (e \cdot 1) + (-4+4e) \cdot 0 & (e \cdot -4) + (-4+4e) \cdot 1 \\ (0 \cdot 1) + (1 \cdot 0) & (0 \cdot -4) + (1 \cdot 1) \end{bmatrix} = \begin{bmatrix} e & -4 \\ 0 & 1 \end{bmatrix}$ As shown,  $e^A e^B \neq e^{A+B}$ .

**Problem 6.** A particular solution to the differential equation

$$\frac{d\vec{u}}{dt} = A\vec{u} - \vec{b},$$

where  $\vec{b}$  is constant, is given by

$$\vec{u}_p = A^{-1}\vec{b}$$

if A is invertible. The complete solution is  $\vec{u}_p + \vec{u}_n$  where  $\vec{u}_n$  are solutions to  $\frac{d\vec{u}}{dt} = A\vec{u}$ . Find the complete solution for the equations:

a)

$$\frac{du}{dt} = u - 4,$$

The general solution  $\mathbf{u}_n$  to the homogeneous equation  $\frac{du}{dt} = u$  is:

$$u_n = Ce^t$$

where C is a constant.

A particular solution  $\mathbf{u}_p$  can be found by assuming  $u_p = k$  where k is a constant. Substituting  $u_p$  into the equation gives:

$$0 = k - 4 \implies k = 4.$$

Thus, the complete solution is:

$$u(t) = u_p + u_n = 4 + Ce^t.$$

$$\frac{d\vec{u}}{dt} = \begin{bmatrix} 1 & 0\\ 1 & 1 \end{bmatrix} \vec{u} - \begin{bmatrix} 4\\ 6 \end{bmatrix}.$$
$$A^{-1} = \begin{bmatrix} 1 & 0\\ -1 & 1 \end{bmatrix}.$$

Multiplying  $A^{-1}$  by  $\vec{b}$  gives the particular solution  $\vec{u}_p$ :

$$\vec{u}_p = A^{-1}\vec{b} = \begin{bmatrix} 4\\2 \end{bmatrix}.$$

The homogeneous solution  $\vec{u}_n$  solves  $\frac{d\vec{u}}{dt} = A\vec{u}$ . The eigenvalues of A are both 1, thus  $\vec{u}_n$  can be written as:

$$\vec{u}_n = C_1 e^t \begin{bmatrix} 0\\1 \end{bmatrix} + C_2 e^t \begin{bmatrix} 1\\1 \end{bmatrix},$$

where  $C_1$  and  $C_2$  are constants.

Hence, the complete solution is:

$$\vec{u}(t) = \vec{u}_p + \vec{u}_n = \begin{bmatrix} 4\\2 \end{bmatrix} + C_1 e^t \begin{bmatrix} 0\\1 \end{bmatrix} + C_2 e^t \begin{bmatrix} 1\\1 \end{bmatrix}.$$

Problem 7. The Pauli matrices are given by

$$\sigma_1 = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \quad \sigma_2 = \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix}, \quad \sigma_3 = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix},$$

a) Show that every self-adjoint matrix  $H = H^*$  can be written as

$$H = aI_2 + b\sigma_1 + c\sigma_2 + d\sigma_3$$

where a, b, c, d are real numbers.

First note that any self-adjoint matrix can be written in terms of the Pauli matrices and the identity matrix.

Let H be a self-adjoint matrix. Then, by definition,  $H^* = H$ . We can write H in terms of the Pauli matrices and the identity matrix as follows:

$$H = aI_2 + b\sigma_1 + c\sigma_2 + d\sigma_3$$

where a, b, c, d are complex numbers.

To show that a, b, c, d must be real, we consider the condition for H to be self-adjoint:

$$H^* = H$$

b)

For H to be self-adjoint, we need:

 $H = H^*$ 

$$aI_2 + b\sigma_1 + c\sigma_2 + d\sigma_3 = a^*I_2 + b^*\sigma_1 + c^*\sigma_2 + d^*\sigma_3$$

Since a, b, c, d are equal to their complex conjugates, they must be real. Therefore, we can write H as

$$H = aI + b\sigma_1 + c\sigma_2 + d\sigma_3$$

where a, b, c, d are real numbers.

b) Compute the eigenvalues of  $b\sigma_1 + c\sigma_2 + d\sigma_3$  and use this to compute the eigenvalues of H. (Hint: Show that  $(b\sigma_1 + c\sigma_2 + d\sigma_3)^2 = (b^2 + c^2 + d^2)I_2$  and note that the trace of  $b\sigma_1 + c\sigma_2 + d\sigma_3$  is zero.)

Let  $B = b\sigma_1 + c\sigma_2 + d\sigma_3$ . We compute:

$$B^{2} = (b\sigma_{1} + c\sigma_{2} + d\sigma_{3})^{2} = b^{2}\sigma_{1}^{2} + c^{2}\sigma_{2}^{2} + d^{2}\sigma_{3}^{2} + (\text{cross terms}).$$

Using properties of Pauli matrices:

$$\sigma_1^2 = \sigma_2^2 = \sigma_3^2 = I_2,$$
  
$$\sigma_i \sigma_j + \sigma_j \sigma_i = 0 \quad \text{for } i \neq j.$$

Thus,  $B^2 = (b^2 + c^2 + d^2)I_2$ . Since  $B^2 = (b^2 + c^2 + d^2)I_2$ , the eigenvalues of B are  $\pm \sqrt{b^2 + c^2 + d^2}$ . Considering  $H = aI_2 + B$ , the eigenvalues of H are:

$$a + \sqrt{b^2 + c^2 + d^2}$$
 and  $a - \sqrt{b^2 + c^2 + d^2}$ .

## Problem 8.

a) Let T be an upper triangular  $n \times n$  matrix with diagonal elements  $a_1, a_2, \ldots, a_n$ . Show that

$$(T - a_1 I)(T - a_2 I) \cdots (T - a_n I) =$$
 zero matrix

In other words, the matrix T is a 'root' of the characteristic polynomial.

Given an upper triangular matrix T, consider the subspace W spanned by the standard basis vectors  $\epsilon_1, \epsilon_2, \ldots, \epsilon_{n-1}$ . This subspace is invariant under the action of T, which means that T maps vectors in W to other vectors in W. The matrix B, which is the representation of T restricted to W, is upper triangular and is obtained by deleting the last row and column of T.

The characteristic polynomial of B is  $g(x) = (x-a_1)(x-a_2)\cdots(x-a_{n-1})$ . By the inductive hypothesis, we assume that g(B) = 0 for matrices of size less than n, which implies  $g(B)\epsilon_i = 0$  for all  $i \leq n-1$ . Considering the characteristic polynomial  $f(x) = (x - a_1)(x - a_2) \cdots (x - a_n)$  of the full matrix T, we have  $f(T) = (T - a_n I)g(T)$ . It follows that  $f(T)\epsilon_i = 0$  for all  $i \leq n - 1$ , given that  $g(T)\epsilon_i = 0$  for these indices.

To show that  $f(T)\epsilon_n = 0$ , we note that  $(T - a_n I)\epsilon_n$  is a linear combination of  $\epsilon_1, \ldots, \epsilon_{n-1}$  due to the upper triangular structure of T. Thus:

$$f(T)\epsilon_n = g(T)(T - a_n I)\epsilon_n = g(T)(r_1\epsilon_1 + \ldots + r_{n-1}\epsilon_{n-1}) = r_1g(T)\epsilon_1 + \ldots + r_{n-1}g(T)\epsilon_{n-1} = 0.$$

As  $f(T)\epsilon_i = 0$  for all basis vectors  $\epsilon_i$ , where i = 1, ..., n, and since the action of a linear operator on the basis vectors determines the operator entirely, it follows that f(T) = 0, the zero matrix.

b) Using the Schur factorization  $A = UTU^*$  where U is unitary and T upper triangular, prove Cayley's theorem which states that the matrix is a root of its characteristic polynomial. More precisely, if the characteristic polynomial of A is given by

$$(-1)^n \lambda^n + (-1)^{n-1} \operatorname{Tr}(A) \lambda^{n-1} + \dots + \det(A)$$

then

$$(-1)^n A^n + (-1)^{n-1} \operatorname{Tr}(A) A^{n-1} + \dots + (\det(A)) I_n = 0$$

From the Schur factorization  $A = UTU^*$ , where T has the eigenvalues of A on its diagonal, we know that T satisfies its characteristic polynomial. Thus, we have

$$(T - \lambda_1 I)(T - \lambda_2 I) \cdots (T - \lambda_n I) = 0,$$

where  $\lambda_i$  are the eigenvalues of A.

The characteristic polynomial  $p(\lambda)$  of A can be written as:

$$p(\lambda) = (-1)^n (\lambda - \lambda_1) (\lambda - \lambda_2) \cdots (\lambda - \lambda_n).$$

Evaluating this polynomial at A gives:

$$p(A) = (-1)^n (A - \lambda_1 I) (A - \lambda_2 I) \cdots (A - \lambda_n I)$$

Substituting A with  $UTU^*$  and considering  $UU^* = I$ , we get:

$$p(A) = (-1)^n (UTU^* - \lambda_1 I) (UTU^* - \lambda_2 I) \cdots (UTU^* - \lambda_n I).$$

By multiplying out these terms and using the fact that T is a root of its characteristic polynomial, we obtain:

$$p(A) = (-1)^n U(T - \lambda_1 I)(T - \lambda_2 I) \cdots (T - \lambda_n I)U^* = 0$$

Thus, A also satisfies its characteristic polynomial.